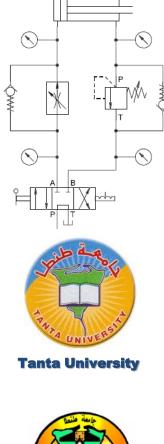


Hydraulic & Pneumatic Circuits





Faculty of Engineering Mechanical power Engineering Dept.

Lecture (3)

on

Components of Hydraulic Action and Control

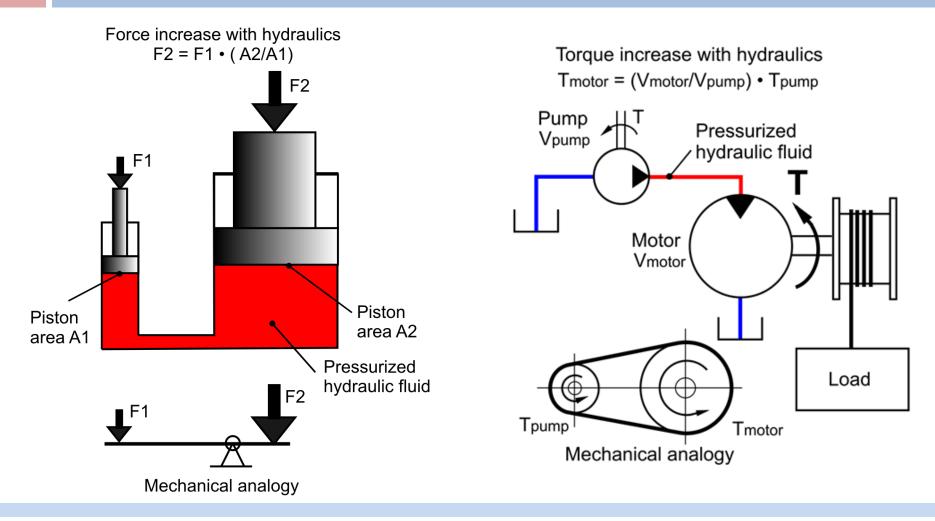
By

Dr. Emad M. Saad

Industrial Engineering Dept. Faculty of Engineering Fayoum University

2014 - 2015



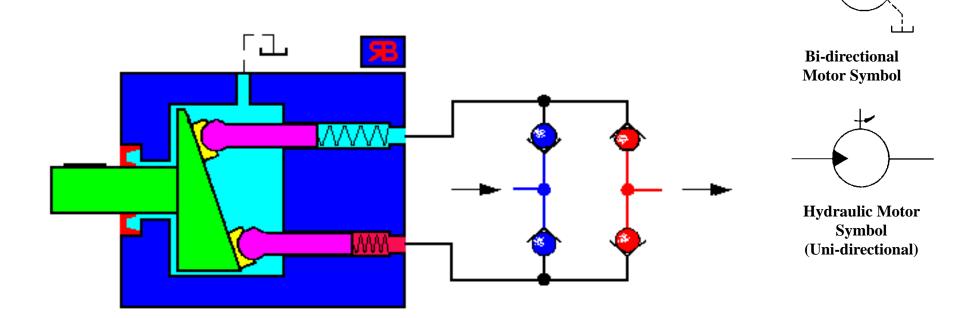






4

Hydraulic motors convert the working energy of a hydraulic system into rotary mechanical energy.







Hydraulic motors selection performance quantities

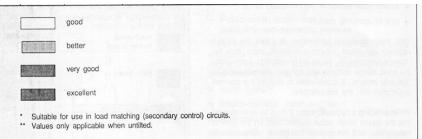
- 1. Speed and speed ranges
- 2. Torque and power, both peak and continuous
- 3. Type of load (constant or fluctuating)
- 4. Type of duty
- 5. Constant or variable displacement
- 6. Angular acceleration
- 7. Swivel times of control systems
- 8. Magnitude of starting torque
- 9. Steady-state motion in the low speed range
- 10. Type of operating medium





Comparison of different types of motor

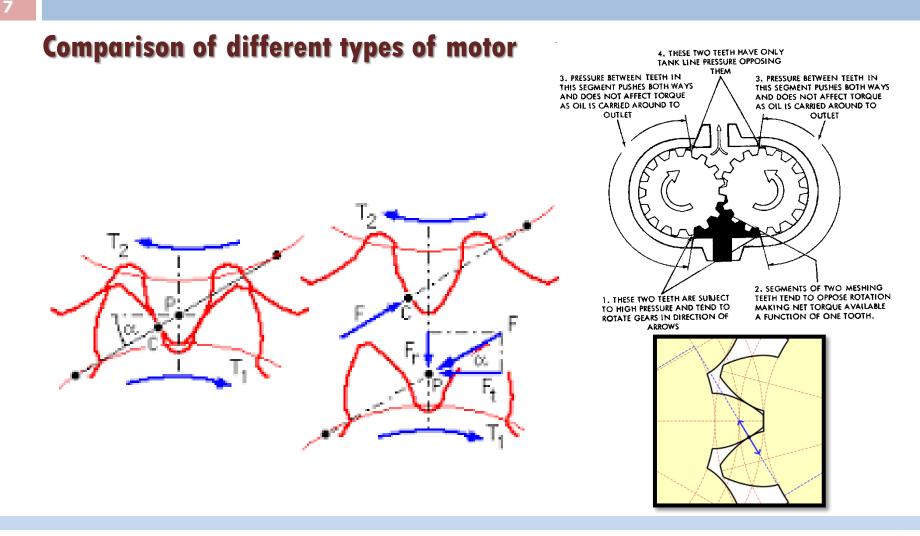
Type of motor			Rexroth designa- tion	Nominal size, i.e. displacement in cm ³	P _{max} > P _{rated} in bar	Speed range according to size in rev/min	Starting charac- teristics	Noise level	Effi- ciency η _{t max}	
	Gear motors			G2 G3	6 to 38	250	500 to 3000			85
Fixed displacement motors	axial piston motors	peed	Bent- axis types	A2FM A2FE A2F/BR5	10 to 250 28 to 180 355 to 1000	450 450 400	50 to 6000 50 to 4750 50 to 2240			92
		high speed	Swash plate types	A4FM	22 and 28	450	30 to 4000			91
		Slow-speed types		MCS MC(4) MC(6)	200 to 1500	250	5 to 500			90
	Orbit-type motors			MZA MZD MZF MZK	60 to 270	225	10 to 1000			85
	Radial	Cam-ring type		MCR	500 to 3000	450	3 to 250			91
	piston motors	Eccentric type		MR	190 to 7000	420	1 to 500		RI. Tel	92
Variable displacement motors	Radial-piston motors			MRV	190 to 7000	420	1 to 500	and the second		92
	Axial	Bent-axis type		A6VM A6V	28 to 355 28 to 107	450	50 to 8000 **			92
	piston motors	Swash-plate type		A10VM A4VS * A10VSO*	45 40 to 250 28 to 71	315 400 315	30 to 3600 ** 6 to 4900 ** 40 to 3600 **			91







Hydraulic Motors - External Gear Motors

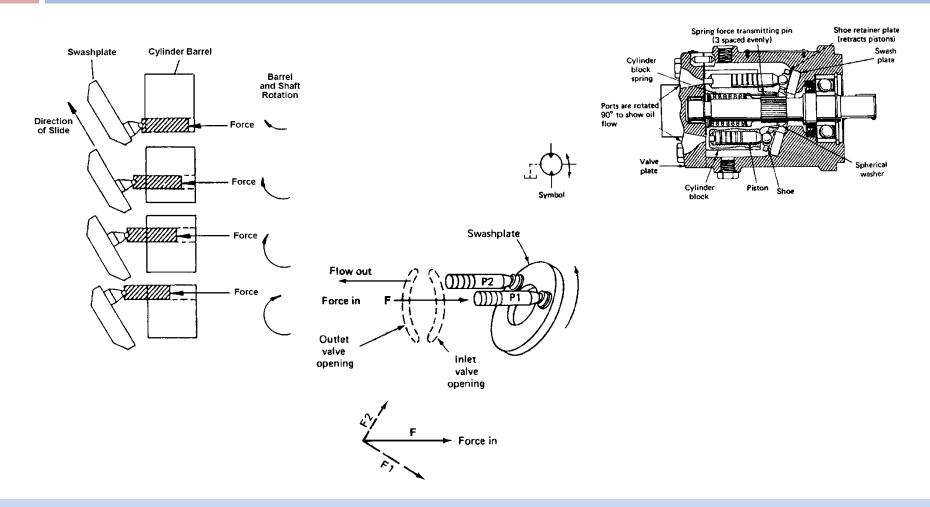




Lecture (3) - Hydraulic and Pneumatic Circuits - 4th year - Mech. power Engineering Dept.



Hydraulic Motors - Axial Piston Motors





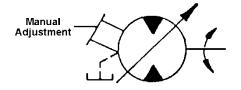


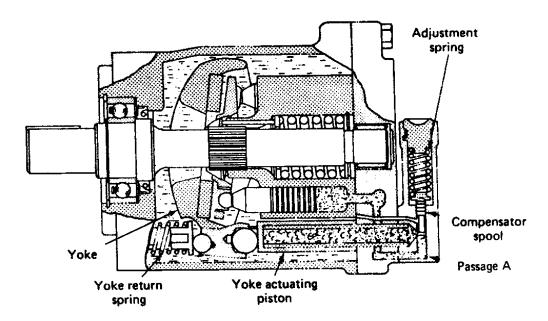


Hydraulic Motors - Axial Piston Motors

Variable Displacement Axial Piston Motors

By varying the angle of the swashplate then, the motor's displacement and consequently its shaft speed and torque output can be changed.

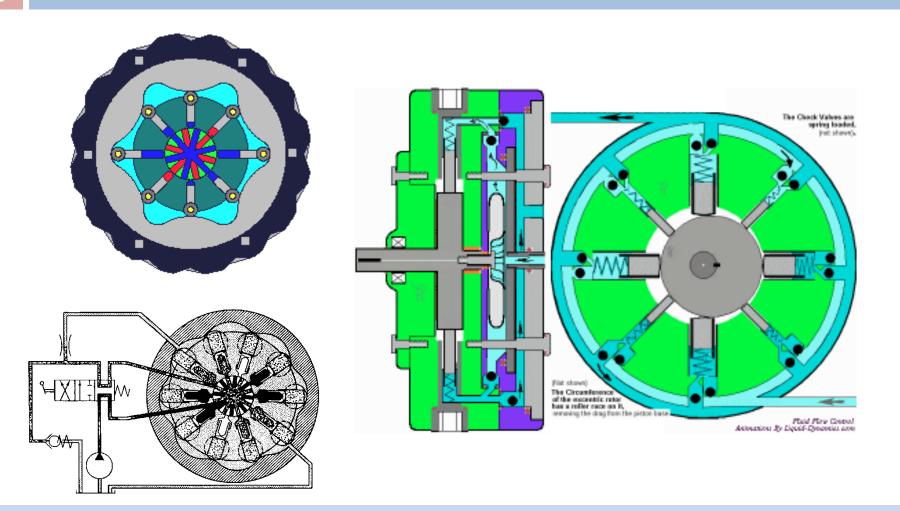








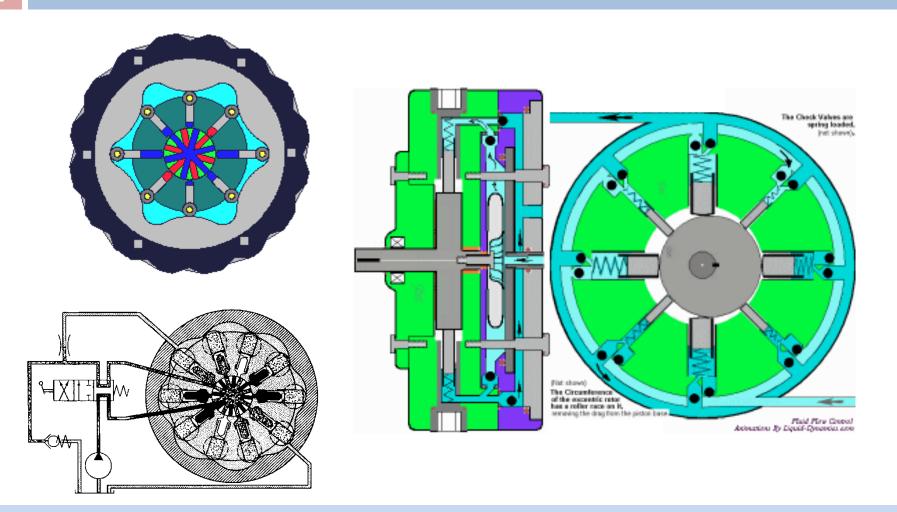
Hydraulic Motors - Radial Piston Motors







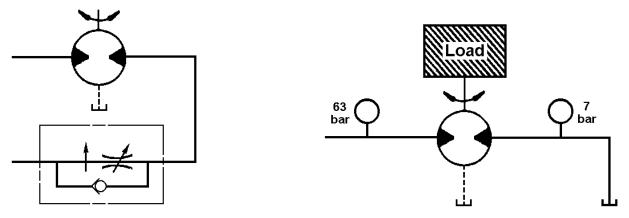
Hydraulic Motors - Radial Piston Motors







Hydraulic Motors in a Circuit



Meter-out with motor

A meter-out circuit controls the flow as it discharges from the motor and is not concerned with leakage. This is the only circuit which can control a motor's shaft speed accurately regardless of load.

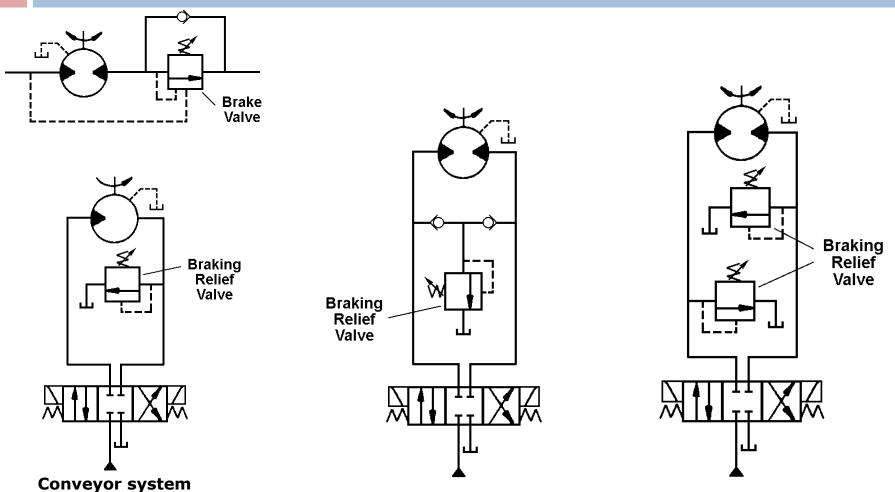
To accurately control the speed of a hydraulic motor, a meter-out circuit is used





Hydraulic Motors in a Circuit – Break valve

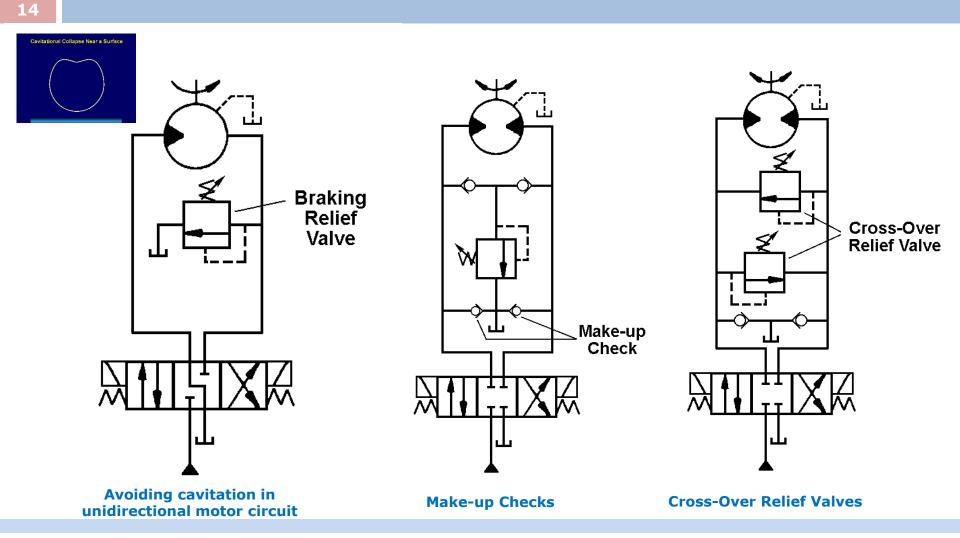
13







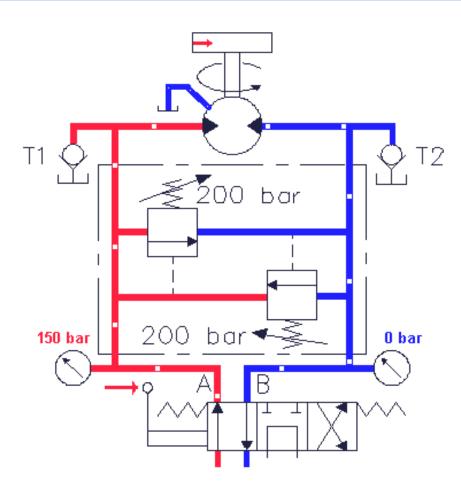
Hydraulic Motors in a Circuit – Motor Cavitation







Hydraulic Motors in a Circuit



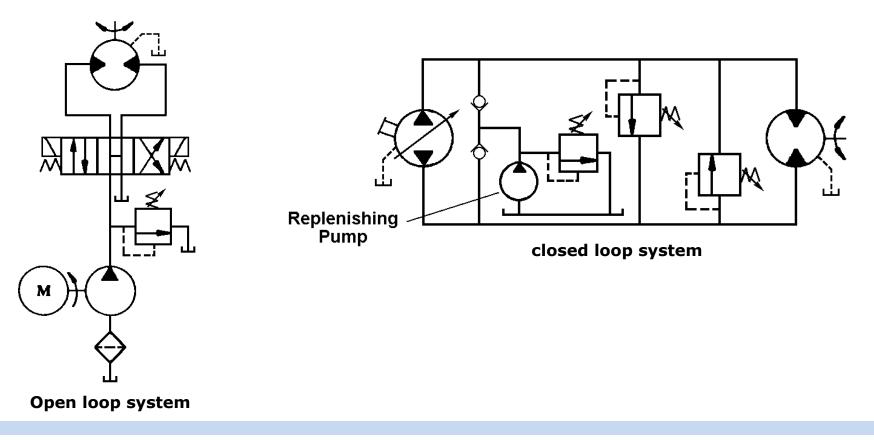




Hydraulic Motors in a Circuit - Hydrostatic Drive

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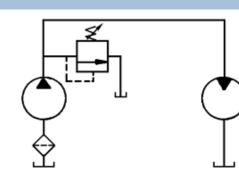
The term hydrostatic refers to the transfer of energy from flow and pressure, not from the kinetic energy of the flow.



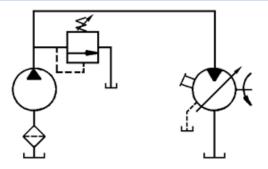




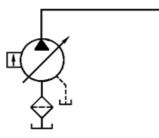
Pump-Motor Combinations



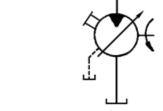
Fixed Hp, Torque and Speed



Fixed Hp, Variable Speed and Torque



Variable Hp and Speed, Constant Torque



Variable Hp, Speed and Torque

Displa	cement	Result				
Pump	Motor	Torque	Speed	Power		
Fixed	Fixed	Fixed	Fixed	Fixed		
Fixed	Variable	Variable	Variable	Fixed		
Variable	Fixed	Fixed	Variable	Variable		
Variable	Variable	Variable	Variable	Variable		





Hydraulic Motors versus Electric Motors

- 18
- **1.** Instant reversing of a motor's shaft
- 2. Stalling for indefinite periods without damage
- 3. Torque control throughout its operating speed
- 4. Dynamic braking easily accomplished
- 5. A weight to horsepower ratio of 2.2 N/hp compared to 44 N/hp for electric motors.
- 6. More flexibility in operating in unfavorable environments. Operation in explosive atmospheres and submerged in liquids is easier to do with hydraulic rather than electric motors.





Hydraulic Motors versus Electric Motors

Otherwise, the commonly used three-phase alternating current electric motors have certain advantages over hydraulic motors. A few are listed below:

- Electric motor efficiency is greater. It may range from 90 to 95 percent.
 Hydraulic motor efficiency may range from 70 to 90 percent.
- 2. Alternating-current motors have better speed regulation than hydraulic motors, since the speed regulation of the electric motor is a function of the line frequency.
- 3. The starting torque of the electric motor is higher.

