Describing Pseudospherical Planes and Other Properties of Evolutionary SolitonEquations

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Abstract: In thispaper we will derive Bäcklund transformations and conservation laws based on geometrical properities of evolution equations with more than two independent variables that describe pseudospherical surfaces.

Keywords: Evolution equations, Pseudospherical surfaces, Bäcklund transformations, conservation laws and Solitons.

I. Introduction

In this paper we, interest in Bäcklund transformation[12], and its connection with some special equations and their associated soliton theory. Under this transformation an infinite family of constant curvature surfaces can be produced from a given one. The notion of a differential equation for a function u(x,t) that describes a pseudospherical surface (P.S.S.) was introduced in [1,6,7], where classifications for some equations of types

$$u_{xt} = \psi \left(u, u_x, u_{xx}, \dots \dots \frac{\partial^k u}{\partial x^k} \right)$$
 and $u_t = \psi \left(u, u_x, \dots \dots \frac{\partial^k u}{\partial x^k} \right)$

Were obtained. Furthermore characterizations of equations with more than two independent variables of types

$$\begin{aligned} u_{xt} &= \psi \left(u, u_x, \dots, \frac{\partial^k u}{\partial x^k}, u_y, \dots, \frac{\partial^k u}{\partial x^k} \right), u_t &= \psi \left(u, u_x, \dots, \frac{\partial^k u}{\partial x^k}, u_y, \dots, \frac{\partial^k u}{\partial x^k} \right) \\ &\text{and} u_{tt} &= \psi \left(u, u_x, \dots, \frac{\partial^k u}{\partial x^k}, u_y, \dots, \frac{\partial^k u}{\partial x^k}, u_t \right) \text{ are given in [2,3,4].} \end{aligned}$$

A systematic procedure to determine linear problems associated to non-linear equations of the abovetypes was also introduced in case of two independent variables.

In this work, we consider evolution equations for a function u(x, y, t) that describes an (η, ξ) 3-dim. P.S.P. as given in [2,3,4] and we investigate an analogous method to derive Bäcklundtransformations and conservation laws based on geometrical properties of these 3- dimensional pseudo spherical planes in \mathbb{R}^5 .

II. Local theory of constant negative curvature submanifolds of R^{2n-1}

Let M be an n-dimensional Riemannian manifold with constant curvature K isometrically immersed in \overline{M}^{2n-1} with constant curvature \overline{K} , with $K \le \overline{K}$. Let $e_1, e_2, \ldots, e_{2n-1}$ be a moving orthonormal frame on an open set of \overline{M} , so that at points of M, e_1, e_2, \ldots, e_n are tangents to M. Let ω_A be the dual orthonormal coframe and consider ω_{AB} defined by [2]

$$de_A = \sum_B \omega_{AB} \, e_B$$

The structure equations of Mare

$$d\omega_A = \sum_B \omega_B \wedge \omega_{BA} \ , \ \omega_{AB} + \omega_{BA} = 0 \eqno(1)$$

$$d\omega_{AB} = \sum_{C} \omega_{AC} \wedge \omega_{CB} - \overline{K}\omega_{A} \wedge \omega_{B} \quad \text{with} \quad 1 \le A, B, C \le 2n - 1 \tag{2}$$

Restricting these forms to M we have $\omega_{\alpha}=0$, so (1) gives with $n+1\leq\alpha, \beta,\gamma\leq 2n-1$ and $1\leq I$, J, L $\leq n$,

$$d\omega_{\alpha} = \sum_{I} \omega_{I} \wedge \omega_{I\alpha} = 0 \tag{3}$$

$$d\omega_I = \sum_I \omega_J \wedge \omega_{JI} \ (4)$$

from (2) we obtain, Gauss equation